

Scalable Gaussian Processes with Billions of Inducing Inputs via Tensor Train Decomposition

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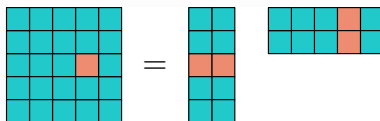
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Tensor Train Decomposition [Oseledets 2011]

- Generalizes low rank approximation

Low-Rank



$$A_{3,4} = u_3^T v_4$$

Tensor Train

A 3D tensor $B_{2,3,1}$ is shown on the left, with one slice highlighted in orange. This is equal to the product of three tensors: u_2^T (a 3x2x2 tensor), v_3 (a 2x3x3 tensor), and w_1 (a 2x2x1 tensor). Each tensor has one slice highlighted in orange.

$$B_{2,3,1} = u_2^T v_3 w_1$$

- Doesn't suffer from curse of dimensionality
- Allows fast implementation of linear algebra operations

ML Applications of TT

- ▶ TensorNet: DNN compression
 - ▶ Feed Forward [Novikov et al. 2015]
 - ▶ Convolutional [Garipov et al. 2016]
 - ▶ Recurrent [Yu et al. 2018]
- ▶ Markov Random Fields [Novikov et al. 2014]
- ▶ Theoretical analysis of RNN expressive power [Khrulkov et al. 2018]
- ▶ Discrete VAE [coming soon]

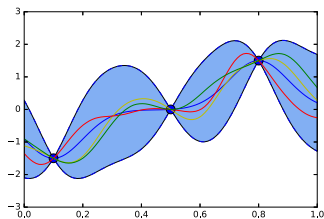
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- ▶ *TT-GP – Scalable GP framework*

Gaussian Processes

Definition

Gaussian process is a collection of random variables, any finite number of which have joint Gaussian distribution.

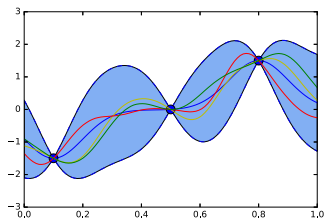


Posterior distribution of a one-dimensional Gaussian process

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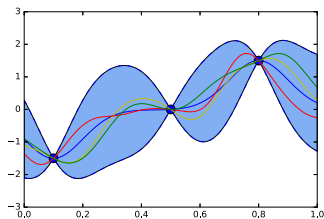
In Machine Learning GPs

- ▶ Allow automatic tuning of model complexity (non-parametric model)
- ▶ Provide principled uncertainty estimates
- ▶ Can discover complex non-linear patterns in data

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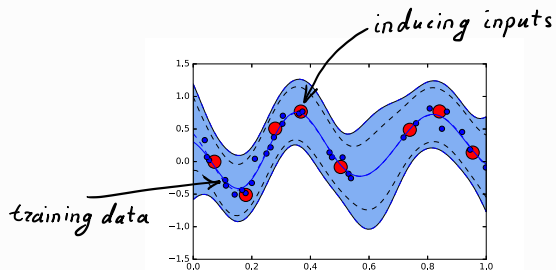


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- ▶ Allow automatic tuning of model complexity (non-parametric model)
- ▶ Provide principled uncertainty estimates
- ▶ Can discover complex non-linear patterns in data
- ▶ Exact inference is $\mathcal{O}(n^3)$

Inducing Inputs



Approximate posterior distribution based on inducing inputs

- ▶ Auxiliary observations that approximate the data
- ▶ Allow fast approximate inference

Previous Methods

- ▶ Classical methods [e.g. Snelson and Ghahramani 2005, Titsias 2009, Hensman et al. 2013] require $\mathcal{O}(nm^2 + m^3)$ computations, m is the number of inducing points
 - ▶ Applicable for large n (e.g. 10^6)
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- ▶ KISS-GP [Wilson and Nickisch 2015] leverages the structure in the covariance matrices; requires $\mathcal{O}(n + m \log m)$ computations, $m = m_0^D$ and D is the number of features
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 - ▶ Infeasible for large $D \gg 4$
- ▶ *Tensor Train GP (TT-GP)* extends KISS-GP to high-dimensional problems
 - ▶ Applicable for large n (e.g. 10^6) and m (e.g. 10^8)
 - ▶ Applicable for larger D (e.g. 10)

ELBO [Hensman et al. 2013]

Evidence Lower Bound (ELBO) for GP regression:

$$\log p(y) \geq \sum_{i=1}^n \left(\log \mathcal{N}(y_i | k_i^T K_{mm}^{-1} \mu, \sigma^2) - \frac{1}{2\sigma^2} (\tilde{K}_{ii} + \text{tr}(k_i^T K_{mm}^{-1} \Sigma K_{mm}^{-1} k_i)) \right) - \frac{1}{2} \left(\log \frac{|K_{mm}|}{|\Sigma|} - m + \text{tr}(K_{mm}^{-1} \Sigma) + \mu^T K_{mm}^{-1} \mu \right) \rightarrow \max_{\mu, \Sigma, \theta, \sigma}$$

where

- ▶ $K_{mm} \in \mathbb{R}^{m \times m}$ is the covariance matrix computed at the inducing points
- ▶ $k_i \in \mathbb{R}^m$ is the vector of covariances between the i -th training object and the inducing points
- ▶ σ^2 is the noise variance
- ▶ $\mu \in \mathbb{R}^m$, $\Sigma \in \mathbb{R}^{m \times m}$ — variational parameters
- ▶ $\tilde{K}_{ii} = \delta^2 - k_i^T K_{mm}^{-1} k_i$, where δ^2 is the prior variance of the process at any point
- ▶ θ represents kernel hyper-parameters

Assume m is very large (e.g. 10^{10})

$$\log p(y) \geq \sum_{i=1}^n \left(\log \mathcal{N}(y_i | \mathbf{k}_i^T \mathbf{K}_{mm}^{-1} \boldsymbol{\mu}, \sigma^2) - \frac{1}{2\sigma^2} (\tilde{K}_{ii} + \text{tr}(\mathbf{k}_i^T \mathbf{K}_{mm}^{-1} \boldsymbol{\Sigma} \mathbf{K}_{mm}^{-1} \mathbf{k}_i)) \right) -$$

$$\frac{1}{2} \left(\log \frac{|\mathbf{K}_{mm}|}{|\boldsymbol{\Sigma}|} - m + \text{tr}(\mathbf{K}_{mm}^{-1} \boldsymbol{\Sigma}) + \boldsymbol{\mu}^T \mathbf{K}_{mm}^{-1} \boldsymbol{\mu} \right)$$

ELBO + KISS-GP [Wilson and Nickisch 2015]

Assume m is very large (e.g. 10^{10})

$$\log p(y) \geq \sum_{i=1}^n \left(\log \mathcal{N}(y_i | \mathbf{w}_i^T \boldsymbol{\mu}, \sigma^2) - \frac{1}{2\sigma^2} (\tilde{K}_{ii} + \text{tr}(\mathbf{w}_i^T \boldsymbol{\Sigma} \mathbf{w}_i)) \right) \\ - \frac{1}{2} \left(\log \frac{|K_{mm}|}{|\boldsymbol{\Sigma}|} - m + \text{tr}(K_{mm}^{-1} \boldsymbol{\Sigma}) + \boldsymbol{\mu}^T K_{mm}^{-1} \boldsymbol{\mu} \right)$$

- ▶ Set inducing points on a grid
- ▶ Assume product kernel
- ▶ K_{mm} is in Kronecker product format
- ▶ $k_i \approx K_{mm} w_i$, w_i in Kronecker product format

TT-GP (Our Method)

$$\log p(y) \geq \sum_{i=1}^n \left(\log \mathcal{N}(y_i | \mathbf{w}_i^T \boldsymbol{\mu}, \sigma^2) - \frac{1}{2\sigma^2} (\tilde{K}_{ii} + \text{tr}(\mathbf{w}_i^T \boldsymbol{\Sigma} \mathbf{w}_i)) \right) \\ - \frac{1}{2} \left(\log \frac{|K_{mm}|}{|\boldsymbol{\Sigma}|} - m + \text{tr}(K_{mm}^{-1} \boldsymbol{\Sigma}) + \boldsymbol{\mu}^T K_{mm}^{-1} \boldsymbol{\mu} \right)$$

Restrict the format of variational parameters:

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Restrict the format of variational parameters:

- Σ in Kronecker product format

$$\Sigma = \Sigma^1 \otimes \Sigma^2 \otimes \dots \otimes \Sigma^D$$

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Restrict the format of variational parameters:

- ▶ Σ in Kronecker product format

$$\Sigma = \Sigma^1 \otimes \Sigma^2 \otimes \dots \otimes \Sigma^D$$

- ▶ μ in TT format
 - ▶ μ naturally reshapes to a tensor

Tensor Train format [Oseledets 2011]

Tensor μ is said to be represented in TT format if:

$$\mu(i_1, \dots, i_D) = \underbrace{G_1[i_1]}_{1 \times r} \underbrace{G_2[i_2]}_{r \times r} \cdots \underbrace{G_D[i_D]}_{r \times 1}, \quad i_k \in \{1, \dots, m_0\}$$

$$\mu_{2423} = G_1 \times G_2 \times G_3 \times G_4$$

$i_1 = 2 \quad i_2 = 4 \quad i_3 = 2 \quad i_4 = 3$

G_k — TT-cores, r — TT-rank

- ▶ TT-format uses $\mathcal{O}(Dm_0r^2)$ memory to approximate a tensor with m_0^D elements
- ▶ Allows efficient implementation of linear algebra operations
- ▶ Generalizes Kronecker product format ($r = 1$)

TT-GP method

- ▶ Set inducing points Z on a grid in the feature space.
- ▶ Σ in Kronecker product format, μ in TT format
- ▶ Maximize the ELBO wrt to
 - ▶ TT-cores of μ
 - ▶ Kronecker factors of Σ
 - ▶ kernel hyper-parameters

Properties of TT-GP

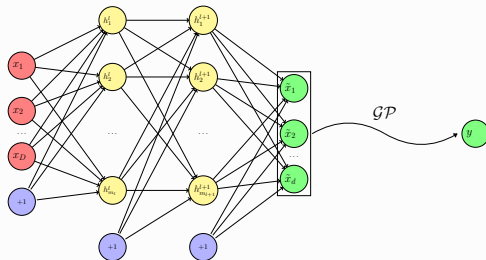
- ▶ Computational complexity

$$\mathcal{O}(nDm^{1/D}r^2 + Dm^{1/D}r^3 + Dm^{3/D});$$

$m = m_0^D$, TT-ranks are on the scale of $r \approx 10$;

- ▶ In the experiments we use up to $n \approx 10^6$, $m \approx 10^{10}$
- ▶ Computationally tractable for large D
 - ▶ For $D \gg 10$ more practical to train embedding

Deep Kernel Embedding [Wilson et al. 2016]



Given base kernel k , e.g. RBF

$$k(x, x') = \alpha^2 \cdot \exp(-\|x - x'\|^2 / \beta^2),$$

define deep kernel as

$$k_{\text{net}}(x, x') = k(\text{net}(x), \text{net}(x')),$$

where k is the base kernel, net is a mapping performed by a DNN.

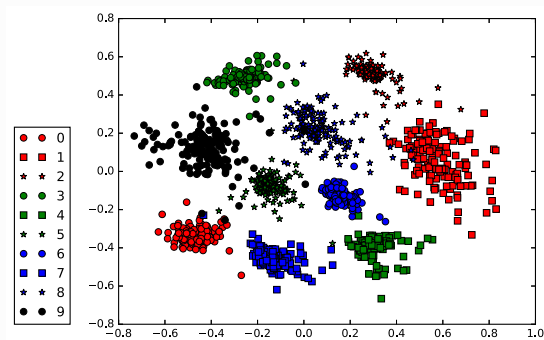
- ▶ DNN weights \rightarrow kernel hyperparameters
- ▶ Train as before

Experiments: RBF kernel

Dataset			SVI-GP / KLSP-GP			TT-GP (Ours)			
Name	n	D	acc.	m	t (s)	acc.	m	d	t (s)
Powerplant	7654	4	0.94	200	10	0.95	35^4	-	5
Protein	36584	9	0.50	200	45	0.56	30^9	-	40
YearPred	463K	90	0.30	1000	597	0.32	10^6	6	105
Airline	$6M$	8	0.665*	-	-	0.694	20^8	-	5200
svmguide1	3089	4	0.967	200	4	0.969	20^4	-	1
EEG	11984	14	0.915	1000	18	0.908	12^{10}	10	10
covtype bin	465K	54	0.817	1000	320	0.852	10^6	6	172

- ▶ SVI-GP – [Hensman et al. 2013]
- ▶ KLSP-GP – [Hensman et al. 2015]

Experiments: Deep Kernel Embedding



Learned representation for the Digits dataset, $n = 1797$, $D = 64$

Experiments: Deep kernels

Dataset		SV-DKL	DNN		TT-GP		
Name	n	acc.	acc.	t (s)	acc.	d	t (s)
Airline	$6M$	0.781	0.780	1055	0.788 ± 0.002	2	1375
CIFAR-10	$50K$	—	0.915	166	0.908 ± 0.003	9	220
MNIST	$60K$	—	0.993	23	0.9936 ± 0.0004	10	64

- SV-DKL — [Wilson et al. 2016]

Discussion

TT-GP

- ▶ Uses Tensor Train decomposition and Kronecker format for variational parameters
- ▶ Scales to large n, m, D
- ▶ Naturally allows training deep kernels

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- ▶ Uses Tensor Train decomposition and Kronecker format for variational parameters
- ▶ Scales to large n, m, D
- ▶ Naturally allows training deep kernels
- ▶ Tends to overestimate uncertainties